# Fluid Dynamic Modeling in Oven Chambers: Balancing Accuracy and Computational Efficiency

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- Reduction of computational complexity by choosing the best model strategy to simulate the fluid dynamics in a closed oven chamber
- Optimization of the process workflow to maximize the efficiency of module usage



The classical way to investigate the forced ventilation and thermal distribution in a closed chamber is to simulate the **coupled CFD and HT** problem in the full domain

A simpler, but less accurate way to make the same investigation is to **separate the study of the driving force (fan) from the effect in the remaining chamber.** 

## How good this accuracy can be?

#### General concept





Steps



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# The analysis is characterized by three steps:

#### Step 1

Need of both CFD and HT modules for the entire simulation time over a complex domain

#### Step 2

Need of only the CFD module for a simplified domain

#### Step 3

Need of the only HT module for the chamber domain (complexity of the fan is excluded)

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Wall Distance Initialization					~									~				~

## Module usage and timing





#### Step 1 – Model characteristics





Temperature is set at the resistors surface (500 degC), thermal dissipation can occur at the door

#### Results - Step 1 – Full oven simulation





#### Step 2 – Model characteristics



Thin faces used to define the fan geometry



Domain setting

Component 1 (comp1)

Air (mat1)
Moving Mesh

Rotating Domain 1

Definitions
Geometry 1
Materials

4







### Step 2 – simplified domain

![](_page_9_Picture_1.jpeg)

![](_page_9_Figure_2.jpeg)

![](_page_9_Figure_3.jpeg)

oven, given to the following value A<sub>outlet</sub> / A<sub>outlet wall</sub> = 0,6470

#### Step 2 – Output quantities

![](_page_10_Picture_1.jpeg)

![](_page_10_Picture_2.jpeg)

These two output profiles of step 1 are the input for step 3

![](_page_11_Picture_1.jpeg)

The door of the oven was open to let the insertion of the pipe. The pipe was placed in front of the fan. A digital anemometer was used to measure the volumetric flow rate.

![](_page_11_Figure_3.jpeg)

Rpm	ṁ experimental (kg/s)	ṁ simulation (kg/s)	shift (%)
1000	0,163	0,153	6,22
1600	0,248	0,247	0,25
2000	0,302	0,311	2,65

![](_page_11_Picture_5.jpeg)

# Velocity and pressure **U** e p – Average over a full rotation step 2 (output)/ step 3 (input)

![](_page_12_Picture_1.jpeg)

Since the frozen rotor captures a snapshot of a specific angular position of the fan, another velocity and pressure profile has been considered by averaging all the quantities along the rotation axis

![](_page_12_Figure_3.jpeg)

#### Step 3 – Model characteristics

![](_page_13_Picture_1.jpeg)

![](_page_13_Figure_2.jpeg)

## Results - Step 3 – Simplified simulation Averaged over full rotation

![](_page_14_Picture_1.jpeg)

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Forno 0611 privato degli elementi superflui e delle ventole, profili mediati.

![](_page_14_Figure_3.jpeg)

#### Results – Velocity profile – step1 vs step2

![](_page_15_Picture_1.jpeg)

We can compare the results in terms of magnitude of field velocity along the lateral surface of the cylinder that defines the frozen rotor domain

![](_page_15_Figure_3.jpeg)

Velocity gradient toward the bottom of the fan is captured by both the models. 16

## Profilo velocità – step1 vs step2

![](_page_16_Picture_1.jpeg)

![](_page_16_Figure_2.jpeg)

![](_page_16_Figure_3.jpeg)

#### Profilo velocità – step1 vs step2

![](_page_17_Picture_1.jpeg)

![](_page_17_Figure_2.jpeg)

### Profilo velocità – step1 vs step2

![](_page_18_Picture_1.jpeg)

![](_page_18_Figure_2.jpeg)

#### General overview – step1 vs step3

![](_page_19_Picture_1.jpeg)

#### Velocity magnitude over different tray level positions

![](_page_19_Figure_3.jpeg)

#### Results Tray 1 position – step 1 vs step 3

![](_page_20_Picture_1.jpeg)

![](_page_20_Figure_2.jpeg)

# Results Tray 2 position – step 1 vs step 3 Step INVENTIVE SIMPLIFICATION Step 3 Mag(U) hystogram at h = 0,2 m from the bottom. Mag(**U**) (m/s) Velocity (m/s) 22

22

1

3

5

6

8

![](_page_22_Figure_0.jpeg)

#### Results Tray 4 position – step 1 vs step 3

![](_page_23_Picture_1.jpeg)

![](_page_23_Figure_2.jpeg)

#### Results Tray 5 position – step 1 vs step 3

![](_page_24_Picture_1.jpeg)

![](_page_24_Figure_2.jpeg)

![](_page_25_Picture_1.jpeg)

Let's consider how off are the mean values for each tray position between the two steps given the previous hystograms

Tray	shift 1-3 (%)
1	6,45
2	5,48
3	5,60
4	3,03
5	2,30
average	4,57

![](_page_26_Picture_1.jpeg)

- 1. The numerical model has been experimentally validated for step 2 and deviation from the experimental values can be considered good.
- 2. The average deviation of the speed distribution in the trays between step 1 and step 3 is less than 5% at all the levels.
- **3.** Qualitatively, the velocity profiles between step 1 and step 2 are very similar, and the main difference is due to loss of some turobent components at the outlet of the fan along the suction axis.

![](_page_27_Picture_1.jpeg)

A good balance between accuracy and computational performances can be achieved by studing the fan alone and then imposing velocity profile and pressure

A better usage of the modules can be achieved differentiating the analysis in different steps as presented

![](_page_27_Picture_4.jpeg)

![](_page_27_Picture_5.jpeg)

![](_page_28_Picture_0.jpeg)

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