

# Ball Check Valve

A ball check valve is a special type of valve in which a unidirectional fluid flow is ensured. In this valve, a movable spring-loaded ball controls the flow. When no inlet pressure is applied, the ball is forced into contact with an O-ring through the preload in the spring. For an inlet pressure imposing a flow in the operating direction, the slit between the ball and the O-ring opens when the fluid force acting on the ball becomes larger than the spring force. In the case of a flow in the opposite direction, the slit between the ball and the O-ring remains closed and the fluid is thus prevented from passing through the valve.

Figure 1 illustrates the fluid flow around the ball at the maximum opening position.

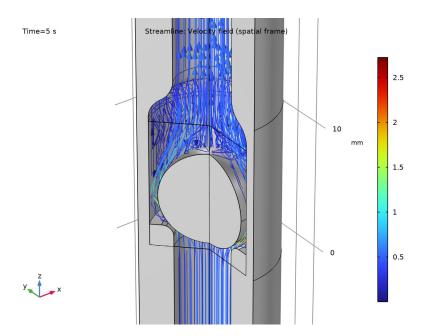


Figure 1: 3D view of the velocity field within the valve at the maximum opening position. The flow is directed upward in the figure.

In this example, you will learn how to solve a structural contact problem where a fluid is surrounding and acting on the potentially contacting solid parts.

The valve is 35 mm long with an outer diameter of 10 mm. The ball chamber inner diameter is 8.4 mm, and the ball diameter is 7.2 mm. The tube inner diameter is 5 mm. The ball chamber length is 10 mm.

The model geometry is reduced to a 2D axisymmetric cut as shown in Figure 2.

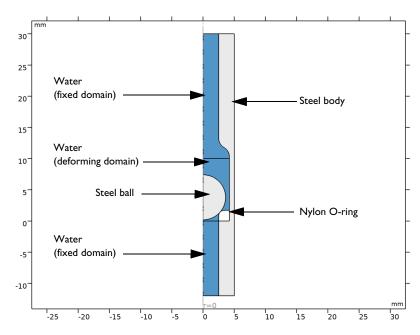


Figure 2: Geometry and materials.

# MATERIAL PROPERTIES

The ball and the valve body are made of steel, the O-ring is made of nylon. The material properties are given in Table 1.

TABLE I: VALVE MATERIAL PROPERTIES

Properties	Structural steel	Nylon
Density	7850 kg/m <sup>3</sup>	II50 kg/m <sup>3</sup>
Young's modulus	200 GPa	2 GPa
Poisson's ratio	0.3	0.4

The fluid used in this study is water at room temperature.

#### **BOUNDARY CONDITIONS**

# Solid Mechanics

The ball is free to move along the symmetry axis and is subjected to both a spring load and to the fluid forces. The fluid forces are automatically applied when using the **Fluid-Structure Interaction** multiphysics coupling. The nylon O-ring is attached to the valve body which is assumed to be rigid. The rigidity is enforced by applying a Fixed Constraint to the entire valve body.

Structural contact between the ball and the O-ring is modeled.

The spring that holds the ball against the O-ring is not represented in the geometry, instead a spring foundation is used. The spring constant is 4 N/m, and the spring is under 5 mm predeformation when the ball is at rest in the valve. To ensure consistent initial conditions, the spring predeformation is ramped up using a smooth step function.

# Turbulent Flow

To study the functioning of the valve, first a reversed flow and then an operating flow are applied. Upstream (bottom) and downstream (top) boundaries are defined as inlet and outlet conditions, respectively, with a varying pressure. The maximum pressure is 25 mbar.

# Moving Mesh

The mesh surrounding the ball is set to deform freely, following a Yeoh mesh smoothing deformation. The mesh displacement is controlled by the structural displacement at the boundaries. At the remaining boundaries, adjacent to the fluid, a fixed boundary is used. Figure 3 shows the fluid velocity at the maximum opening of the valve. The maximum velocity is about 2.7 m/s and the main flow path and the recirculation flow around it are clearly visible.

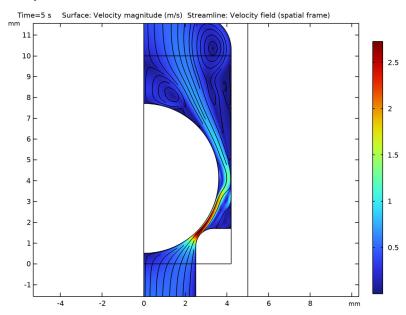


Figure 3: Fluid velocity at the maximum opening of the valve.

Figure 4 shows the pressure distribution in the fluid and the von Mises stress in the solid at maximum opening of the valve.

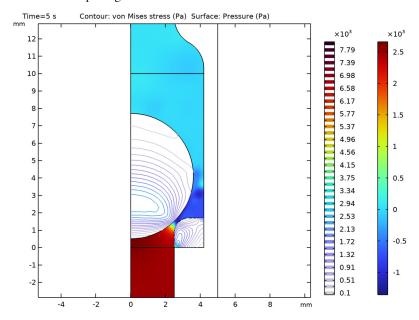


Figure 4: Fluid pressure and von Mises stress at maximum opening of the valve.

Figure 5 and Figure 6 show the fluid pressure when the valve is closed and under maximum pressure in the reverse direction.

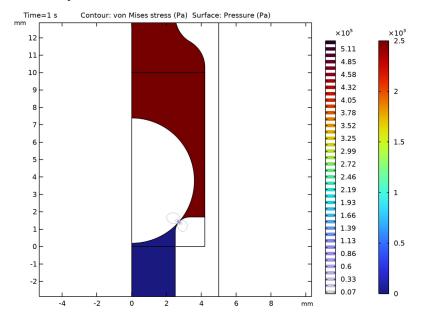


Figure 5: Fluid pressure and von Mises stress at maximum reversed pressure.

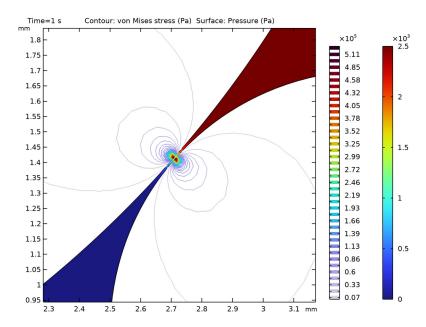


Figure 6: Fluid pressure and von Mises stress at maximum reverse pressure (close-up view of the contact region).

The fluid pressure drop when the flow is blocked in the contact region is clearly visible. The contact is almost localized as a single point contact.



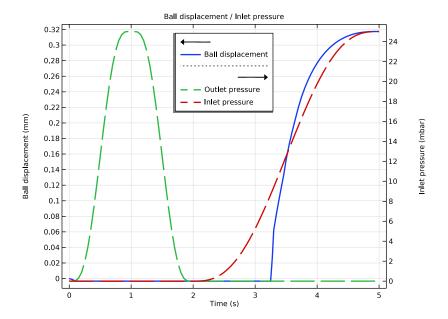
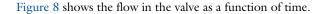


Figure 7: Ball center displacement versus time. The inlet pressures are shown for reference.

The ball moves down slightly as the spring predeformation is applied. As the reverse pressure increases, the displacement of the ball is negligible. After 2 s, the flow in the operating direction is increased until the ball reaches a maximum displacement of about 0.32 mm.



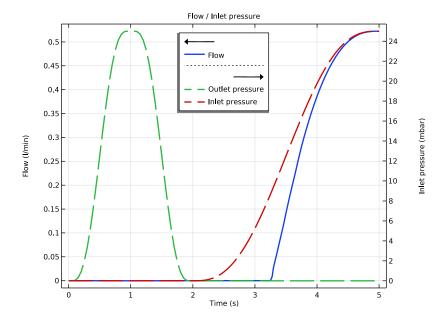
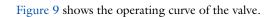


Figure 8: Fluid flow in the valve versus time.

Up to 1 s, the pressure is imposed in the reversed flow direction. The maximum reverse flow is about 0.3 ml/min. This small value is explained by the clearance between the parts in contact which is necessary to avoid topology changes in the fluid domain (see the section Notes About the COMSOL Implementation for more details). The reversed flow can be decreased even more by reducing the contact offset value, at the price of extra solution time caused by mesh refinement.



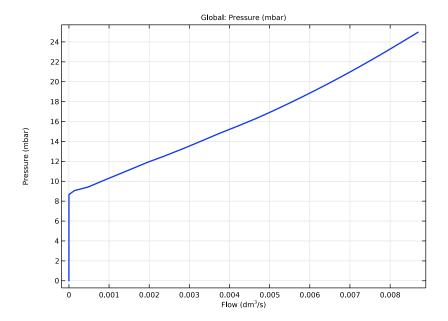


Figure 9: Operating curve of the valve.

From this plot, the opening pressure is seen to be about 9 mbar.

Figure 10 shows the fluid pressure drop in the valve together with the inlet pressure conditions applied during the analysis.

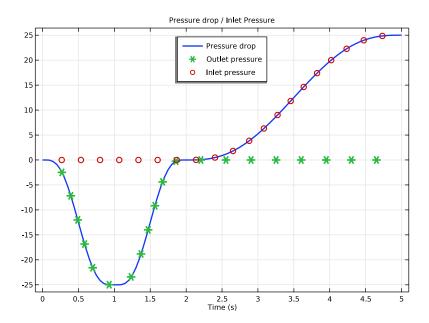


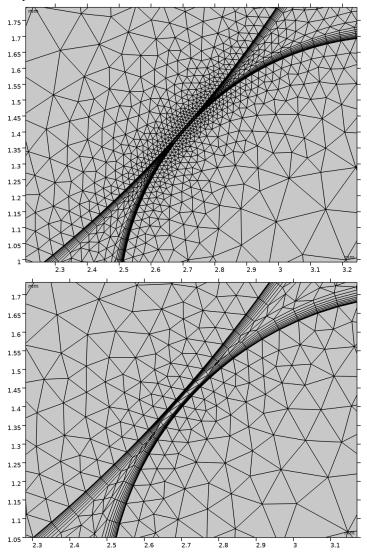
Figure 10: Pressure drop in the valve and inlet pressure condition at top boundary/ downstream (dashed green) and bottom/upstream boundary (dashed red).

# Notes About the COMSOL Implementation

The main purpose of this model is to show how to solve a fluid structure interaction where two elastic parts separated by a fluid can get in contact with each other. The Arbitrary Lagrangian Eulerian (ALE) formulation used for the discretization of the Navier-Stokes equations in a deforming domain requires that the topology of this domain does not change. In a real contact situation, the topology of the fluid domain changes as the parts get into contact. For a numerical analysis, you need to include an offset in the contact settings to prevent the parts to get into physical contact. In this model, the offset is set to a very small value (5 µm) which is sufficient to preserve the fluid-domain topology while still preventing any significant flow in the reverse direction when the valve is closed.

To obtain a good accuracy of the solution, automatic remeshing is used when the ball is getting into contact with the O-ring or is moving away. Because of boundary layer mesh, it is recommended to use distortion as condition for remeshing, here the geometry is remeshed when the square root of the maximum element distortion exceeds 2. Figure 11

shows the different meshes generated by the Automatic Remeshing node during the computation.



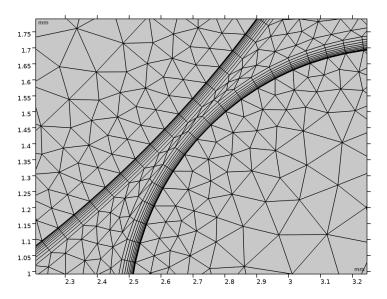


Figure 11: Mesh cases used during the computation (from top to bottom, left to right).

In order to ensure proper restart after the automatic remeshing, it is important to well refine the mesh at the fluid-structure interface. Moreover in the solver settings you can enforce consistent initialization.

The Fluid-Solid Interaction multiphysics interface adds a **Deforming Domain** node where you define the fluid domains to be controlled by structural deformation at their boundaries. In this model, the displacement of the ball is confined, and it is a good idea to split the fluid region into three domains. The central fluid domain (the one containing the moving ball) uses a freely moving deformed mesh, while the bottom and top fluid domains use a fixed mesh. This way you restrict the computation of the moving mesh equations to a minimum.

In this particular example, the valve body is actually modeled as rigid, so except for the contact region it could have been removed from the model entirely. Keeping it will, however, allow better visualization of the model and results.

In the Fluid-Structure Interaction multiphysics coupling, all boundaries between fluid and solid are selected as a default. You could choose to remove the boundaries adjacent to the rigid domains. Here the coupling type has instead been changed to Fluid loading on **structure** to avoid adding the extra degrees of freedoms that would be added for a bidirectional coupling in a fixed geometry case.

Application Library path: Structural Mechanics Module/Fluid-Structure\_Interaction/ball\_check\_valve

# Modeling Instructions

From the File menu, choose New.

#### NEW

In the New window, click Model Wizard.

# MODEL WIZARD

- I In the Model Wizard window, click 2D Axisymmetric.
- 2 In the Select Physics tree, select Fluid Flow > Single-Phase Flow > Turbulent Flow > Turbulent Flow, Algebraic yPlus (spf).
- 3 Click Add.
- 4 In the Velocity field (m/s) text field, type u\_fluid.
- **5** In the **Velocity field components** table, enter the following settings:
- u fluid v fluid w fluid
- 6 In the Select Physics tree, select Fluid Flow > Fluid-Structure Interaction > Fluid-Solid Interaction.
- 7 Click Add.
- 8 In the Added physics interfaces tree, select Laminar Flow (spf2).
- 9 Right-click and choose Remove.
- 10 Click Study.
- II In the Select Study tree, select Preset Studies for Selected Physics Interfaces > Turbulent Flow, Algebraic yPlus > Time Dependent with Initialization.
- 12 Click **Done**.

#### **GLOBAL DEFINITIONS**

# Parameters 1

- I In the Model Builder window, under Global Definitions click Parameters I.
- 2 In the Settings window for Parameters, locate the Parameters section.
- **3** In the table, enter the following settings:

Name	Expression	Value	Description
r1	2.5[mm]	0.0025 m	Inner radius
r2	4.2[mm]	0.0042 m	Ball chamber inner radius
r3	3.6[mm]	0.0036 m	Ball radius
1	12[mm]	0.012 m	Ball chamber length
p0	25[mbar]	2500 Pa	Maximum inlet pressure
k0	4[N/m]	4 N/m	Spring constant
10	5[mm]	0.005 m	Spring predeformation
offset	5[um]	5E-6 m	Contact offset

# GEOMETRY I

- I In the Model Builder window, under Component I (compl) click Geometry I.
- 2 In the Settings window for Geometry, locate the Units section.
- 3 From the Length unit list, choose mm.

# Rectangle I (rI)

- I In the Geometry toolbar, click Rectangle.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- 3 In the Width text field, type r1.
- 4 In the Height text field, type 7/2\*1.
- **5** Locate the **Position** section. In the **z** text field, type -1.

# Rectangle 2 (r2)

- I In the Geometry toolbar, click Rectangle.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- 3 In the Width text field, type r2-r1.
- 4 In the Height text field, type 1.
- **5** Locate the **Position** section. In the **r** text field, type r1.

Union I (uni I)

- I In the Geometry toolbar, click Booleans and Partitions and choose Union.
- 2 Click in the **Graphics** window and then press Ctrl+A to select both objects.
- 3 In the Settings window for Union, locate the Union section.
- 4 Clear the Keep interior boundaries checkbox.

Fillet I (fill)

- I In the **Geometry** toolbar, click **Fillet**.
- 2 On the object unil, select Point 8 only.
- 3 In the Settings window for Fillet, locate the Radius section.
- 4 In the Radius text field, type r2-r1.

Fillet 2 (fil2)

- I In the Geometry toolbar, click / Fillet.
- 2 On the object fill, select Point 5 only.
- 3 In the Settings window for Fillet, locate the Radius section.
- 4 In the Radius text field, type r2-r1.

Square I (sql)

- I In the Geometry toolbar, click Square.
- 2 In the Settings window for Square, locate the Size section.
- 3 In the Side length text field, type r2-r1.
- 4 Locate the Position section. In the r text field, type r1.

Fillet 3 (fil3)

- I In the **Geometry** toolbar, click **Fillet**.
- 2 On the object sql, select Point 4 only.
- 3 In the Settings window for Fillet, locate the Radius section.
- 4 In the Radius text field, type (r2-r1)/2.

Circle I (c1)

- I In the Geometry toolbar, click Circle.
- 2 In the Settings window for Circle, locate the Size and Shape section.
- 3 In the Radius text field, type r3.
- 4 In the Sector angle text field, type 180.
- 5 Locate the **Position** section. In the z text field, type r3.

6 Locate the Rotation Angle section. In the Rotation text field, type -90. You will now create imprints at the expected contact location.

Partition Domains I (bard1)

- I In the Geometry toolbar, click Booleans and Partitions and choose **Partition Domains.**
- **2** On the object **c1**, select Domain 1 only.
- **3** On the object **fil3**, select Domain 1 only.
- 4 In the Settings window for Partition Domains, locate the Partition Domains section.
- **5** Click to select the **Activate Selection** toggle button for Vertices defining line segments.
- 6 From the Partition with list, choose Edges.
- 7 On the object c1, select Boundary 1 only.
- 8 On the object fil3, select Boundary 5 only.

Move I (movI)

- I In the Geometry toolbar, click Transforms and choose Move.
- 2 Select the object pardI(I) only.
- 3 In the Settings window for Move, locate the Displacement section.
- 4 In the z text field, type 0.19 to ensure a clearance slightly above the contact offset.

Union 2 (uni2)

- I In the Geometry toolbar, click Booleans and Partitions and choose Union.
- 2 Select the objects mov! and pard!(2) only.
- 3 In the Settings window for Union, locate the Union section.
- 4 Clear the **Keep interior boundaries** checkbox.

Create a domain for the moving mesh.

Line Segment I (Is I)

- I In the Geometry toolbar, click \* More Primitives and choose Line Segment.
- 2 In the Settings window for Line Segment, locate the Starting Point section.
- 3 From the Specify list, choose Coordinates.
- 4 Locate the Endpoint section. From the Specify list, choose Coordinates.
- 5 In the r text field, type r1.

- Centroid Measurement 1 (cm1)

  I In the Geometry toolbar, click Measurements and choose Centroid Measurement.
- 2 On the object fil2, select Point 9 only.

Line Segment 2 (Is2)

- I In the Geometry toolbar, click More Primitives and choose Line Segment.
- 2 In the Settings window for Line Segment, locate the Starting Point section.
- 3 From the Specify list, choose Coordinates.
- 4 In the z text field, type geom1.cm1.z.
- 5 Locate the **Endpoint** section. From the **Specify** list, choose **Coordinates**.
- 6 In the r text field, type geom1.cm1.r.
- 7 In the z text field, type geom1.cm1.z.

Form Union (fin)

- I In the Model Builder window, click Form Union (fin).
- 2 In the Settings window for Form Union/Assembly, click 📳 Build Selected.
- 3 Click the **Zoom Extents** button in the **Graphics** toolbar.

# ADD MATERIAL

- I In the Materials toolbar, click Radd Material to open the Add Material window.
- 2 Go to the Add Material window.
- 3 In the tree, select Built-in > Water, liquid.
- 4 Right-click and choose Add to Component I (compl).
- 5 In the tree, select Built-in > Nylon.
- 6 Right-click and choose Add to Component I (compl).
- 7 In the tree, select Built-in > Structural steel.
- 8 Right-click and choose Add to Component I (compl).
- 9 In the Materials toolbar, click **# Add Material** to close the Add Material window.

# MATERIALS

Nylon (mat2)

- I Select Domain 5 only.
- 2 In the Settings window for Material, click to expand the Appearance section.
- 3 From the Material type list, choose Plastic.

Structural steel (mat3)

- I In the Model Builder window, click Structural steel (mat3).
- 2 Select Domain 3 only.
- 3 In the Settings window for Material, click to expand the Appearance section.
- 4 From the Material type list, choose Steel.
- 5 In the Model Builder window, click Materials.
- 6 In the Settings window for Materials, in the Graphics window toolbar, click ▼ next to Colors, then choose Show Material Color and Texture.

# MOVING MESH

Deforming Domain I

- I In the Model Builder window, under Component I (compl) > Moving Mesh click Deforming Domain 1.
- 2 Select Domain 2 only.

Prescribed Normal Mesh Displacement I

- I In the Moving Mesh toolbar, click / Prescribed Normal Mesh Displacement.
- 2 Select Boundaries 3 and 7 only.

#### DEFINITIONS

Piecewise I (pw I)

- I In the **Definitions** toolbar, click  $\bigwedge$  **Piecewise**.
- 2 In the Settings window for Piecewise, type p\_outlet in the Function name text field.
- 3 Locate the **Definition** section. From the **Smoothing** list, choose Continuous second derivative.
- 4 From the Transition zone list, choose Absolute size.
- 5 In the Size of transition zone text field, type 0.45.
- **6** Find the **Intervals** subsection. In the table, enter the following settings:

Start	End	Function
-1	0.5	0
0.5	1.5	p0
1.5	5	0

7 Locate the **Units** section. In the **Arguments** text field, type s.

8 In the Function text field, type Pa.

Piecewise 2 (pw2)

- I In the **Definitions** toolbar, click A **Piecewise**.
- 2 In the Settings window for Piecewise, type p\_inlet in the Function name text field.
- 3 Locate the **Definition** section. From the **Smoothing** list, choose Continuous second derivative.
- 4 From the Transition zone list, choose Absolute size.
- 5 In the Size of transition zone text field, type 1.5.
- **6** Find the **Intervals** subsection. In the table, enter the following settings:

Start	End	Function
0	3.5	0
3.5	7	p0

- 7 Locate the **Units** section. In the **Arguments** text field, type s.
- 8 In the Function text field, type Pa.

Step I (step I)

- I In the **Definitions** toolbar, click f(X) **More Functions** and choose **Step**.
- 2 In the Settings window for Step, type predef in the Function name text field.
- 3 Locate the Parameters section. In the Location text field, type 0.5[s].
- **4** In the **To** text field, type -10.
- 5 Click to expand the Smoothing section. In the Size of transition zone text field, type 1.

Integration I (intob I)

- I In the **Definitions** toolbar, click Nonlocal Couplings and choose Integration.
- 2 In the Settings window for Integration, locate the Source Selection section.
- 3 From the Geometric entity level list, choose Boundary.
- 4 Select Boundary 10 only.

Integration 2 (intob2)

- I In the **Definitions** toolbar, click Monlocal Couplings and choose Integration.
- 2 In the Settings window for Integration, locate the Source Selection section.
- 3 From the Geometric entity level list, choose Point.
- **4** Select Point 7 only.
- 5 Locate the Advanced section. Clear the Compute integral in revolved geometry checkbox.

# Variables 1

- I In the Model Builder window, right-click Definitions and choose Variables.
- 2 In the Settings window for Variables, locate the Variables section.
- **3** In the table, enter the following settings:

Name	Expression	Unit	Description
flow	<pre>intop1(w_fluid)</pre>	m³/s	Flow

# TURBULENT FLOW, ALGEBRAIC YPLUS (SPF)

- I In the Model Builder window, under Component I (compl) click Turbulent Flow, Algebraic yPlus (spf).
- 2 Select Domains 1, 2, and 4 only.
- 3 In the Settings window for Turbulent Flow, Algebraic yPlus, locate the Turbulence section.
- 4 From the Wall treatment list, choose Low Re.

## Inlet I

- I In the Physics toolbar, click Boundaries and choose Inlet.
- 2 Select Boundary 2 only.
- 3 In the Settings window for Inlet, locate the Boundary Condition section.
- **4** From the list, choose **Pressure**.
- **5** Locate the **Pressure Conditions** section. In the  $p_0$  text field, type  $p_i$  in let (t).
- **6** Clear the **Suppress backflow** checkbox.

## Outlet 1

- I In the Physics toolbar, click Boundaries and choose Outlet.
- 2 Select Boundary 10 only.
- 3 In the Settings window for Outlet, locate the Pressure Conditions section.
- **4** In the  $p_0$  text field, type p\_outlet(t).
- 5 Clear the Suppress backflow checkbox.

# SOLID MECHANICS (SOLID)

- I In the Model Builder window, under Component I (compl) click Solid Mechanics (solid).
- **2** Select Domains 3 and 5 only.

# Spring Foundation I

I In the Physics toolbar, click **Domains** and choose **Spring Foundation**.

- 2 Select Domain 3 only.
- 3 In the Settings window for Spring Foundation, locate the Spring section.
- 4 From the Spring type list, choose Total spring constant.
- 5 From the list, choose Diagonal.
- **6** Specify the  $\mathbf{k}_{tot}$  matrix as



# Predeformation I

- I In the Physics toolbar, click \_\_\_ Attributes and choose Predeformation.
- 2 In the Settings window for Predeformation, locate the Spring Predeformation section.
- **3** Specify the  $\mathbf{u}_0$  vector as



# Fixed Constraint I

- I In the Physics toolbar, click Boundaries and choose Fixed Constraint.
- 2 Select Boundaries 13 and 16 only.

You will now set up the contact condition between the ball and the O-ring.

# DEFINITIONS

Contact Pair I (pl)

- I In the Definitions toolbar, click Pairs and choose Contact Pair.
- 2 Select Boundary 23 only.
- 3 In the Settings window for Pair, locate the Destination Boundaries section.
- **4** Click to select the **Activate Selection** toggle button.
- **5** Select Boundary 22 only.

# SOLID MECHANICS (SOLID)

#### Contact I

I In the Model Builder window, under Component I (compl) > Solid Mechanics (solid) click Contact I.

- 2 In the Settings window for Contact, click to expand the Contact Surface Offset and Adjustment section.
- 3 In the  $d_{\text{offset,d}}$  text field, type offset to prevent the part from getting physically in contact. This way, the topology of the moving mesh domain is kept.

### MESH I

- I In the Model Builder window, under Component I (compl) click Mesh I.
- 2 In the Settings window for Mesh, locate the Physics-Controlled Mesh section.
- 3 From the Element size list, choose Fine.
- 4 Click III Build All.

#### STUDY I

# Steb 2: Time Dependent

- I In the Settings window for Time Dependent, locate the Study Settings section.
- 2 In the Output times text field, type range (0,5e-2,5).
- 3 Click to expand the **Results While Solving** section. Select the **Plot** checkbox.
- 4 From the Update at list, choose Time steps taken by solver.
- 5 Click to expand the **Study Extensions** section. Select the **Automatic remeshing** checkbox.

# Solution I (soll)

- I In the Study toolbar, click Show Default Solver.
- 2 In the Model Builder window, expand the Solution I (soll) node.
- 3 In the Model Builder window, expand the Study I > Solver Configurations > Solution I (soll) > Dependent Variables 2 node, then click Pressure (compl.p).
- 4 In the Settings window for Field, locate the Scaling section.
- 5 From the Method list, choose Manual.
- 6 In the Scale text field, type 1e3.
- 7 In the Model Builder window, under Study I > Solver Configurations > Solution I (soll) > Dependent Variables 2 click Spatial Mesh Displacement (compl.spatial.disp).
- 8 In the Settings window for Field, locate the Scaling section.
- 9 In the Scale text field, type 1e-3.
- 10 In the Model Builder window, under Study 1 > Solver Configurations > Solution 1 (soll) > Dependent Variables 2 click Velocity Field (Spatial Frame) (compl.u\_fluid).
- II In the **Settings** window for **Field**, locate the **Scaling** section.

- 12 From the Method list, choose Manual.
- I3 In the Scale text field, type 1.
- 14 In the Model Builder window, under Study 1 > Solver Configurations > Solution 1 (sol1) > Dependent Variables 2 click Displacement Field (compl.u\_solid).
- 15 In the Settings window for Field, locate the Scaling section.
- 16 In the Scale text field, type 1e-3.
- 17 In the Model Builder window, under Study I > Solver Configurations > Solution I (soll) click Time-Dependent Solver 1.
- 18 In the Settings window for Time-Dependent Solver, click to expand the Time Stepping section.
- 19 From the Steps taken by solver list, choose Intermediate.
- 20 In the Model Builder window, expand the Study I > Solver Configurations > Solution I (soll) > Time-Dependent Solver I node, then click Automatic Remeshing.
- 21 In the Settings window for Automatic Remeshing, locate the Condition for Remeshing section.
- **22** From the Condition type list, choose Distortion.
- 2 Locate the Remesh section. From the Consistent initialization list, choose Backward Euler.
- **24** Click **Compute**.

#### RESULTS

# Velocity (spf)

The default plot shows the fluid velocity inside the valve at maximum opening.

#### Streamline 1

- I In the Model Builder window, right-click Velocity (spf) and choose Streamline.
- 2 In the Settings window for Streamline, locate the Streamline Positioning section.
- **3** From the **Positioning** list, choose **Uniform density**.
- 4 In the Separating distance text field, type 0.01.
- 5 In the Velocity (spf) toolbar, click Plot.

# Contour

- I In the Model Builder window, expand the Results > Pressure (spf) node, then click
- 2 In the Settings window for Contour, locate the Expression section.
- 3 In the Expression text field, type solid.mises.

4 Locate the Coloring and Style section. From the Color table list, choose PrismDark.

# Surface I

- I In the Model Builder window, right-click Pressure (spf) and choose Surface.
- 2 In the Settings window for Surface, locate the Expression section.
- **3** In the **Expression** text field, type p.
- 4 In the Pressure (spf) toolbar, click Plot.

- I In the Results toolbar, click  $\sim$  ID Plot Group.
- 2 In the Settings window for ID Plot Group, type Flow in the Label text field.
- 3 Locate the Data section. From the Dataset list, choose Study 1/ Remeshed Solution I (sol3).
- 4 Locate the Legend section. Clear the Show legends checkbox.

# Global I

- I Right-click Flow and choose Global.
- 2 In the Settings window for Global, locate the y-Axis Data section.
- **3** In the table, enter the following settings:

Expression	Unit	Description
flow	1/min	Flow

- 4 Click to expand the **Title** section. From the **Title type** list, choose **Manual**.
- 5 In the **Title** text area, type Flow (solid).
- 6 Click to expand the Coloring and Style section. From the Width list, choose 2.

# Global 2

- I In the Model Builder window, right-click Flow and choose Global.
- 2 In the Settings window for Global, locate the y-Axis Data section.
- **3** In the table, enter the following settings:

Expression	Unit	Description
p_outlet(t)	mbar	Outlet pressure

- 4 Locate the Coloring and Style section. Find the Line style subsection. From the Line list, choose Dashed.
- 5 From the Width list, choose 2.

# Global 3

- I Right-click Flow and choose Global.
- 2 In the Settings window for Global, locate the y-Axis Data section.
- **3** In the table, enter the following settings:

Expression	Unit	Description
p_inlet(t)	mbar	Inlet pressure

- 4 Locate the Coloring and Style section. Find the Line style subsection. From the Line list, choose Dashed.
- **5** From the **Width** list, choose **2**.
- **6** Locate the **Title** section. From the **Title type** list, choose **None**.

# Flow

- I In the Model Builder window, click Flow.
- 2 In the Settings window for ID Plot Group, click to expand the Title section.
- 3 From the Title type list, choose Manual.
- 4 In the **Title** text area, type Flow / Inlet pressure.
- **5** Locate the **Plot Settings** section. Select the **Two y-axes** checkbox.
- 6 In the table, select the Plot on secondary y-axis checkboxes for Global 2 and Global 3.
- 7 Select the **Secondary y-axis label** checkbox. In the associated text field, type Inlet pressure (mbar).
- 8 Locate the Legend section. Select the Show legends checkbox.
- **9** From the **Position** list, choose **Upper middle**.
- **10** In the **Flow** toolbar, click **Plot**.

# Ball Displacement

- I In the Results toolbar, click  $\sim$  ID Plot Group.
- 2 In the Settings window for ID Plot Group, type Ball Displacement in the Label text field.
- 3 Locate the Data section. From the Dataset list, choose Study 1/ Remeshed Solution I (sol3).

# Point Graph 1

- I Right-click Ball Displacement and choose Point Graph.
- **2** Select Point 4 only.

- 3 In the Settings window for Point Graph, locate the y-Axis Data section.
- **4** In the **Expression** text field, type w solid.
- 5 Select the **Description** checkbox. In the associated text field, type Ball displacement.
- 6 Click to expand the Coloring and Style section. From the Width list, choose 2.
- 7 Click to expand the **Legends** section. Select the **Show legends** checkbox.
- 8 From the Legends list, choose Manual.
- **9** In the table, enter the following settings:

Legends	
Ball	displacement

Global 2, Global 3

- I In the Model Builder window, under Results > Flow, Ctrl-click to select Global 2 and Global 3.
- 2 Right-click and choose Copy.

# Ball Displacement

- I In the Model Builder window, under Results right-click Ball Displacement and choose Paste Multiple Items.
- 2 In the Settings window for ID Plot Group, locate the Title section.
- 3 From the Title type list, choose Manual.
- 4 In the Title text area, type Ball displacement / Inlet pressure.
- 5 Locate the Plot Settings section. Select the Two y-axes checkbox.
- 6 Select the Secondary y-axis label checkbox. In the associated text field, type Inlet pressure (mbar).
- 7 In the table, select the Plot on secondary y-axis checkboxes for Global 2 and Global 3.
- 8 Locate the Legend section. From the Position list, choose Upper middle.
- **9** In the **Ball Displacement** toolbar, click  **Plot**.

# Operating Curve

- I In the Home toolbar, click **Add Plot Group** and choose ID Plot Group.
- 2 In the Settings window for ID Plot Group, type Operating Curve in the Label text field.
- 3 Locate the Data section. From the Dataset list, choose Study 1/ Remeshed Solution I (sol3).
- **4** Locate the **Legend** section. Clear the **Show legends** checkbox.

# Global I

- I Right-click Operating Curve and choose Global.
- 2 In the Settings window for Global, locate the y-Axis Data section.
- **3** In the table, enter the following settings:

Expression	Unit	Description
p_inlet(t)	mbar	Pressure

- 4 Locate the x-Axis Data section. From the Parameter list, choose Expression.
- **5** In the **Expression** text field, type flow.
- 6 From the Unit list, choose dm^3/s.
- 7 Locate the Coloring and Style section. From the Width list, choose 2.
- 8 In the Operating Curve toolbar, click **Plot**.

# Pressure Drob

- I In the Results toolbar, click  $\sim$  ID Plot Group.
- 2 In the Settings window for ID Plot Group, type Pressure Drop in the Label text field.
- 3 Locate the Data section. From the Dataset list, choose Study 1/ Remeshed Solution I (sol3).
- 4 Locate the Title section. From the Title type list, choose Manual.
- 5 In the **Title** text area, type Pressure drop / Inlet Pressure.
- 6 Locate the Legend section. From the Position list, choose Upper middle.

# Point Graph 1

- I Right-click Pressure Drop and choose Point Graph.
- 2 Select Point 1 only.
- 3 In the Settings window for Point Graph, locate the y-Axis Data section.
- **4** In the **Expression** text field, type p-intop2(p).
- **5** From the **Unit** list, choose **mbar**.
- **6** Select the **Description** checkbox. In the associated text field, type **Pressure** drop.
- 7 Locate the Coloring and Style section. From the Width list, choose 2.
- **8** Locate the **Legends** section. Select the **Show legends** checkbox.
- 9 From the Legends list, choose Manual.

**10** In the table, enter the following settings:

Legends		
Pressure	drop	

Global 2, Global 3

- I In the Model Builder window, under Results > Flow, Ctrl-click to select Global 2 and Global 3.
- 2 Right-click and choose Copy.

# Pressure Drop

In the Model Builder window, under Results right-click Pressure Drop and choose Paste Multiple Items.

# Global 2

- I In the Settings window for Global, locate the y-Axis Data section.
- **2** In the table, enter the following settings:

Expression	Unit	Description
-p_outlet(t)	mbar	Outlet pressure

- 3 Locate the Coloring and Style section. Find the Line style subsection. From the Line list, choose None.
- 4 Find the Line markers subsection. From the Marker list, choose Cycle.
- 5 From the Positioning list, choose Interpolated.
- 6 In the Number text field, type 20.

# Global 3

- I In the Model Builder window, click Global 3.
- 2 In the Settings window for Global, locate the Coloring and Style section.
- 3 Find the Line style subsection. From the Line list, choose None.
- 4 Find the Line markers subsection. From the Marker list, choose Cycle.
- 5 From the Positioning list, choose Interpolated.
- 6 In the Number text field, type 20.
- 7 In the Pressure Drop toolbar, click  **Plot**.

In the following steps you will generate the plot shown in Figure 1.

# Surface

I In the Model Builder window, expand the Velocity, 3D (spf) node, then click Surface.

- 2 In the Settings window for Surface, locate the Expression section.
- **3** In the **Expression** text field, type 1.
- **4** Click to expand the **Title** section. From the **Title type** list, choose **None**.

# Material Appearance 1

- I Right-click Surface and choose Material Appearance.
- 2 In the Settings window for Material Appearance, locate the Appearance section.
- 3 From the Material list, choose Nylon (mat2).

# Selection I

- I Right-click Surface and choose Selection.
- 2 Select Domain 5 only.

# Surface 2

- I In the Model Builder window, right-click Velocity, 3D (spf) and choose Surface.
- 2 In the Settings window for Surface, locate the Expression section.
- **3** In the **Expression** text field, type 1.

# Material Appearance 1

- I Right-click Surface 2 and choose Material Appearance.
- 2 In the Settings window for Material Appearance, locate the Appearance section.
- 3 From the Material list, choose Structural steel (mat3).

#### Selection 1

- I In the Model Builder window, right-click Surface 2 and choose Selection.
- **2** Select Domain 3 only.

# Streamline 1

- I In the Model Builder window, right-click Velocity, 3D (spf) and choose Streamline.
- 2 In the Settings window for Streamline, locate the Streamline Positioning section.
- **3** From the **Positioning** list, choose **Uniform density**.
- 4 In the Separating distance text field, type 0.02.
- 5 Locate the Coloring and Style section. Find the Point style subsection. From the Type list, choose Arrow.

# Color Expression 1

Right-click Streamline I and choose Color Expression.

Velocity, 3D (spf)

In the Velocity, 3D (spf) toolbar, click Plot.